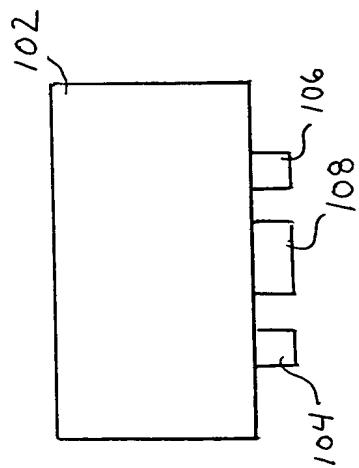


100 ~



200 ~

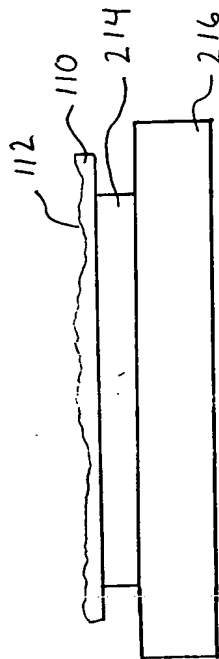
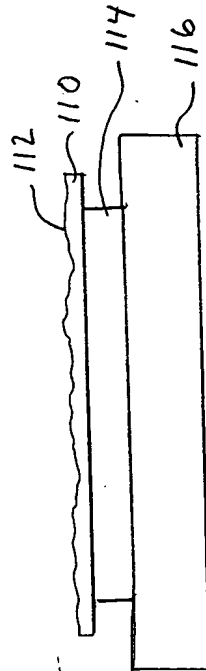
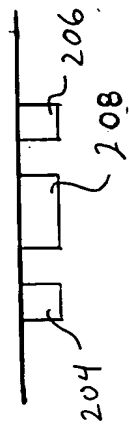


FIG. 1

FIG. 2

FIG. 3A

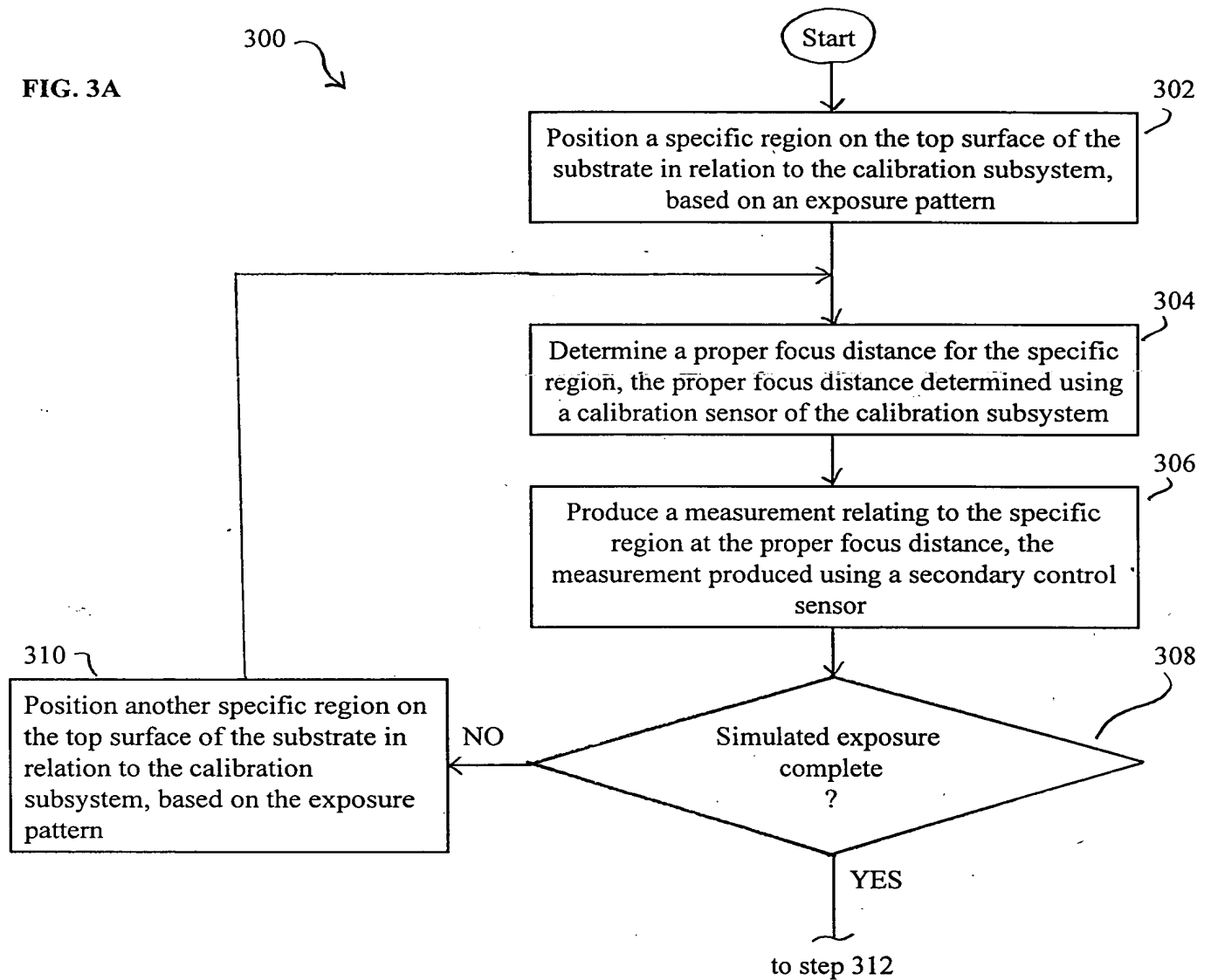
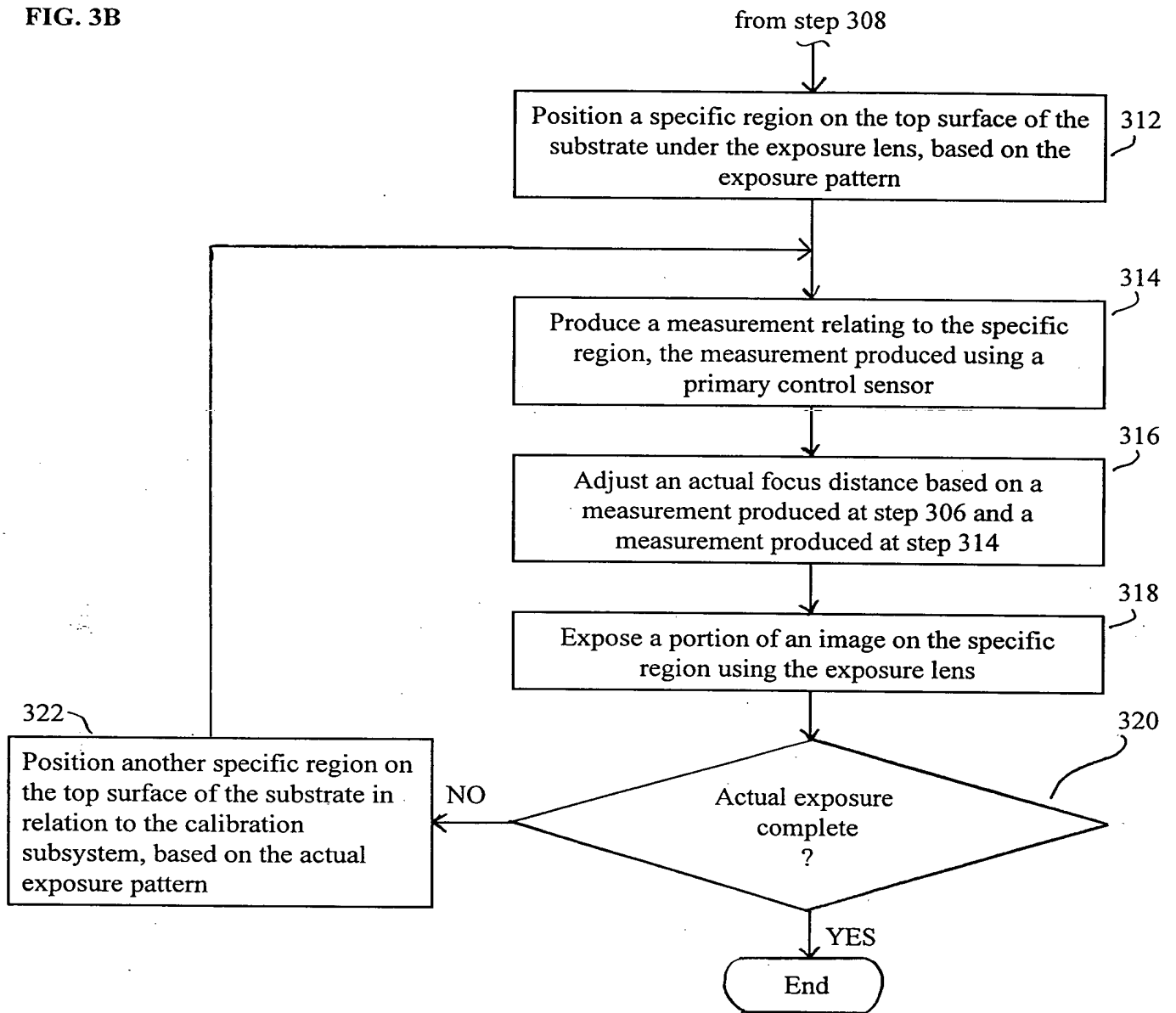


FIG. 3B



402		404		406		406n	
X/Y Coordinates	Calibration Sensor Value (optional)	Control Sensor A Value	Control Sensor B Value	.....	Control Sensor N Value		
$X_1/Y_1$	Calibration <sub>1,1</sub>	ControlA <sub>1,1</sub> (i.e., x=1, y=1)	ControlB <sub>1,1</sub>		ControlN <sub>1,1</sub>		
$X_1/Y_2$	Calibration <sub>1,2</sub>	ControlA <sub>1,2</sub> (i.e., x=1, y=2)	ControlB <sub>1,2</sub>		ControlN <sub>1,2</sub>		
$X_1/Y_3$	Calibration <sub>1,3</sub>	ControlA <sub>1,3</sub>	ControlB <sub>1,3</sub>		ControlN <sub>1,3</sub>		
.	.	.	.		.		
.	.	.	.		.		
$X_2/Y_1$	Calibration <sub>2,1</sub>	ControlA <sub>2,1</sub>	ControlB <sub>2,1</sub>		ControlN <sub>2,1</sub>		
$X_2/Y_2$	Calibration <sub>2,2</sub>	ControlA <sub>2,2</sub>	ControlB <sub>2,2</sub>		ControlN <sub>2,2</sub>		
$X_2/Y_3$	Calibration <sub>2,3</sub>	ControlA <sub>2,3</sub>	ControlB <sub>2,3</sub>		ControlN <sub>2,3</sub>		
.	.	.	.		.		
.	.	.	.		.		
$X_3/Y_1$	Calibration <sub>3,1</sub>	ControlA <sub>3,1</sub>	ControlB <sub>3,1</sub>		ControlN <sub>3,1</sub>		
$X_3/Y_2$	Calibration <sub>3,2</sub>	ControlA <sub>3,2</sub>	ControlB <sub>3,2</sub>		ControlN <sub>3,2</sub>		
$X_3/Y_3$	Calibration <sub>3,3</sub>	ControlA <sub>3,3</sub>	ControlB <sub>3,3</sub>		ControlN <sub>3,3</sub>		
.	.	.	.		.		
.	.	.	.		.		

FIG. 4